

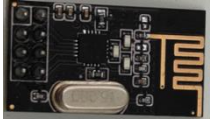




## Packing List

### 1. Electronic Module

Picture	Name	Quantity
	Adeept Robot Control Board	1
	Handle Controller	1
	OLED Screen	1
	ESP8266	1
	SR-04 Ultrasonic Module	1
	3-CH line tracing module	1

	IR remote control	1
	Light Tracking Module	1
	LED matrix	1
	WS2812 LED	1
	RGB LED	2
	18650 Battery Holder	2
	MPU6050	1
	NRF24L01 Module (built-in antenna)	2
	9V battery	1
	9V Battery Holder	1

## 2. Transmission Parts

Servo x2



DC Motor x2



Front Wheel x2



Rear Wheel x2



## 3. Machinery Parts

### Hex nuts





M1.6	x4
M2	x18
M3	x24
M4	x2



### Round head screw

M1.6*10	x4
M2*8	x8
M2*10	x4
M2*14	x8
M3*5	x8

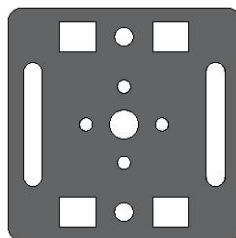


M2.5	x3		M3*8	x28	
			M3*12	x5	
			M3*14	x3	
			M3*30	x4	
			M4*40	x2	
			M2.5*11	x4	
<b>Copper Standoff</b>			<b>Mechanical parts bearings</b>		
M3*6	x2		F624ZZ Bearing	x4	
M3*8	x4				
M2*11	x4				
M3*12	x6				
M3*18	x2				
M3*30	x8				
<b>Spring Washer</b>			<b>Countersunk head screw</b>		
M4 Spring Washer	x8		M3*14	x5	

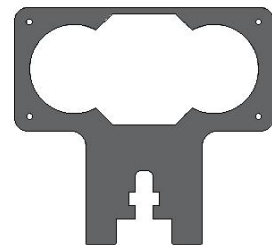
## 4. Acrylic Structural



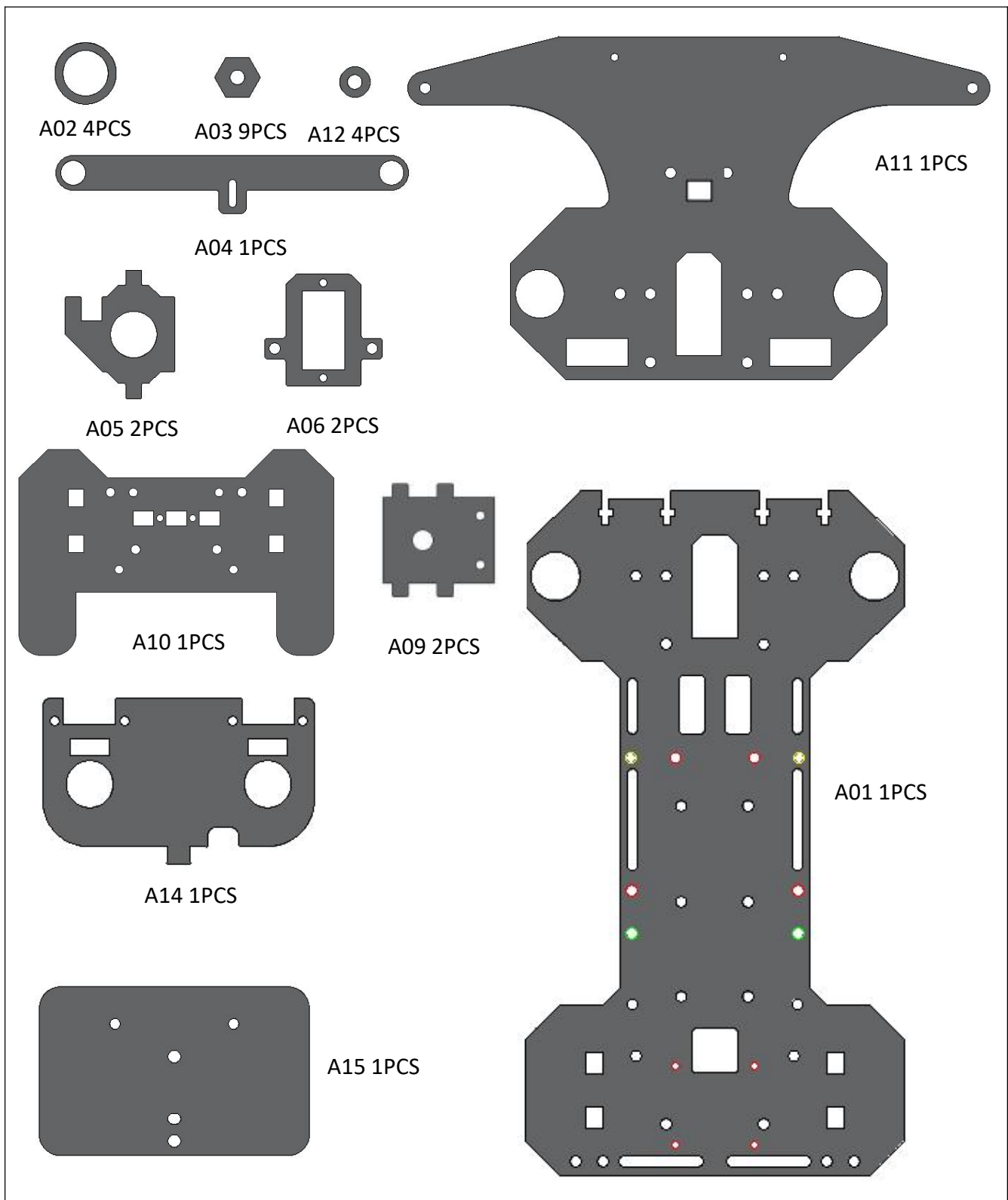
A13 1PCS



A07 1PCS










A08 1PCS









The acrylic board is covered with a layer of protective film. You need to remove it first.

Some holes in the acrylic board have residues, so you need to clean them before using it.

## 5. Connect Cable

Picture	Description	Quantity
	5Pin(Line Tracking) 18cm	1
	4Pin(OLED) 15cm	1
	4Pin(Ultrasound)15cm	1
	4Pin(RGB) 13cm	2
	4Pin(LED Matrix) 18cm	1
	3Pin(Light Tracking) 19cm	1
	3Pin(WS2812) 20cm	1

## 6. Tools

Picture	Name	Description	Quantity
	Wrench	Cross Socket Wrench	1
	Screwdriver	M3 Phillips screwdriver	1
	Screwdriver	M1.5 Phillips screwdriver	1
	USB Cable	Micro USB	1
	USB Cable	Type-C USB	1
 Winding Pipe    ×1			